n p k design

strategic product innovation

Marcel Vroom – project owner @ npk Research project for a rose-nursery Al-robot

EIP project: designing for sustainable agriculture (2024 – 2026) 'Mildew detection by an autonomous sensor system using AI'











Innovation that matters.

At npk, we craft breakthrough products that set brands apart.

Since 1978 we've fused design, technology and strategy to help global leaders create lasting impact.

npk

ASML

★ Heineken

PHILIPS

DELL

Haier

SIEMENS

Míele

Kraft*Heinz*

Canon

(LG

Unilever

Nikon

covestro

C Kimberly-Clark

revvity

BIOTRONIK

GRUNDIG

АТОМІС

Merck

KIL.







Saint-Gobain Cultilene CARA MET Sensor to view in real-time moisture content, EC and Temperature (MET)



Octalarm-TouchAlarm detector for monitoring critical technical processes, like in horticulture



TechnolutionSense2Grow climate sensor



Condifood

Improve food quality and safety with their hyperspectral imaging technology



H2ARVESTER

Mobile solar panels on agricultural land while maintaining agricultural production (agri-PV)

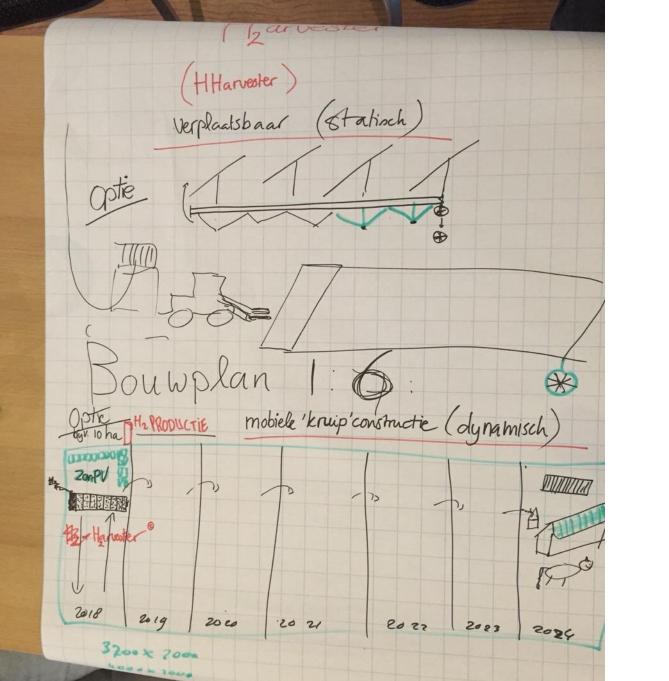
Generating sustainable energy on agricultural land and producing hydrogen on the farm

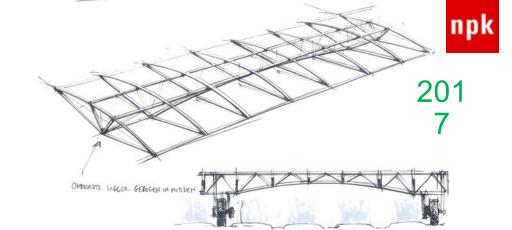














H2ARVESTER

2022









2023

- 18 NOVEMBER | HANOVER, GERMANY
PREVIEW DAYS 12/13 NOVEMBER

- +sensor platforn
- +crop monitoring
- +soil monitoring
- +seeding & weeding
- +drip irrigation
- +arable farm & tree nursery
- +fossil-free farming







Al-powered disease detection for a future without fungicides:
Recognizing powdery and downy mildew in Laxa seedlings, using sensor data from a self-driving sensor car and the use of biostimulants..





Year 1

Year 2





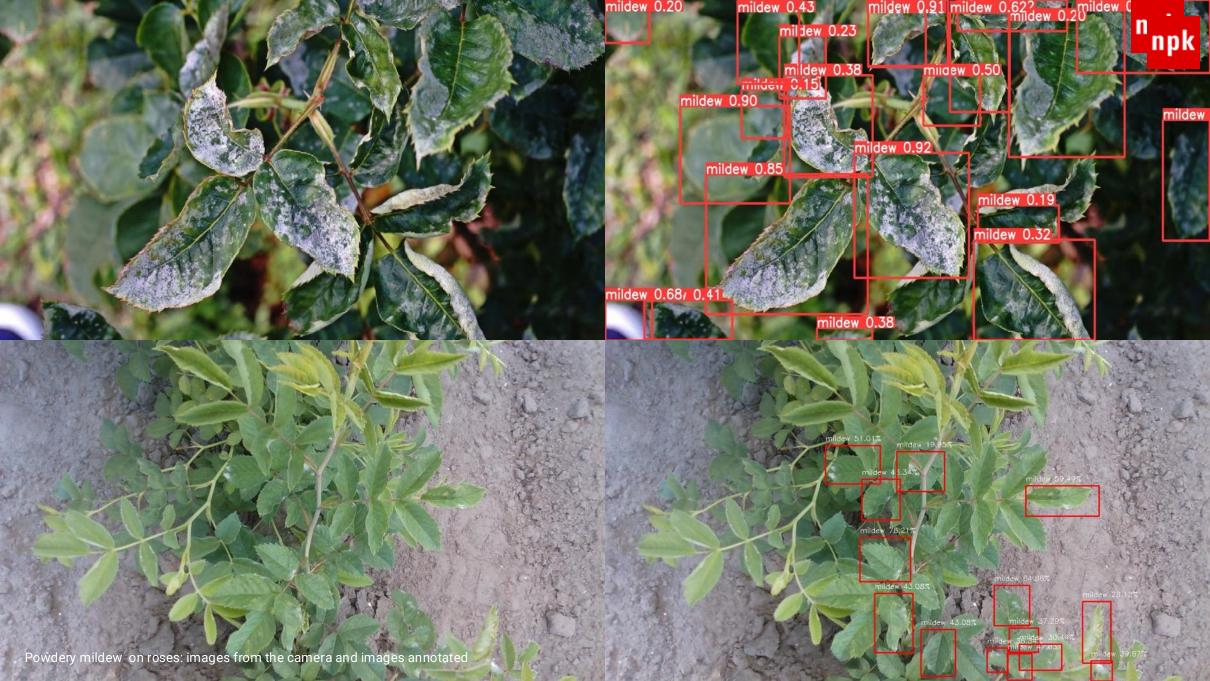




Laxa seedlings

Roos cultivar

Laxa



Farm Dashboard

Farm Health Dashboard

Filters

Collection Date -

All Collections

Camera Type -

RealSense

Processed Only

Refresh Map

Process All Unprocessed

Location: Grubbenvorst

Coordinates: 51.432380, 6.107287

Collections Summary

2025-06-16

Total: 102, realsense: 61, zed2i: 41

Processed: 2

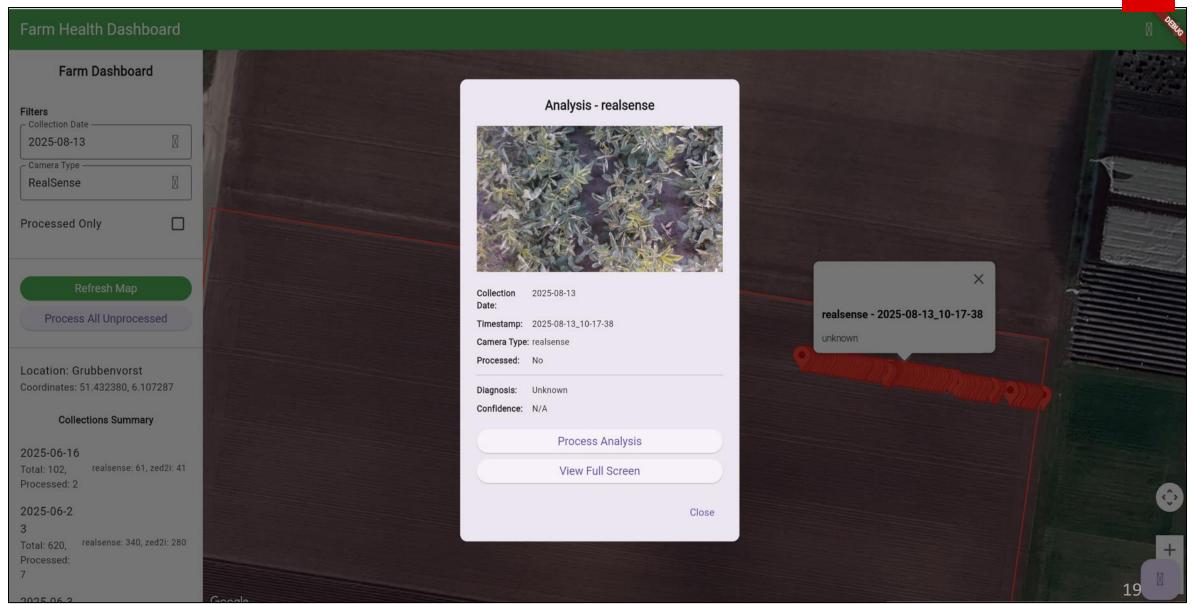
2025-06-2

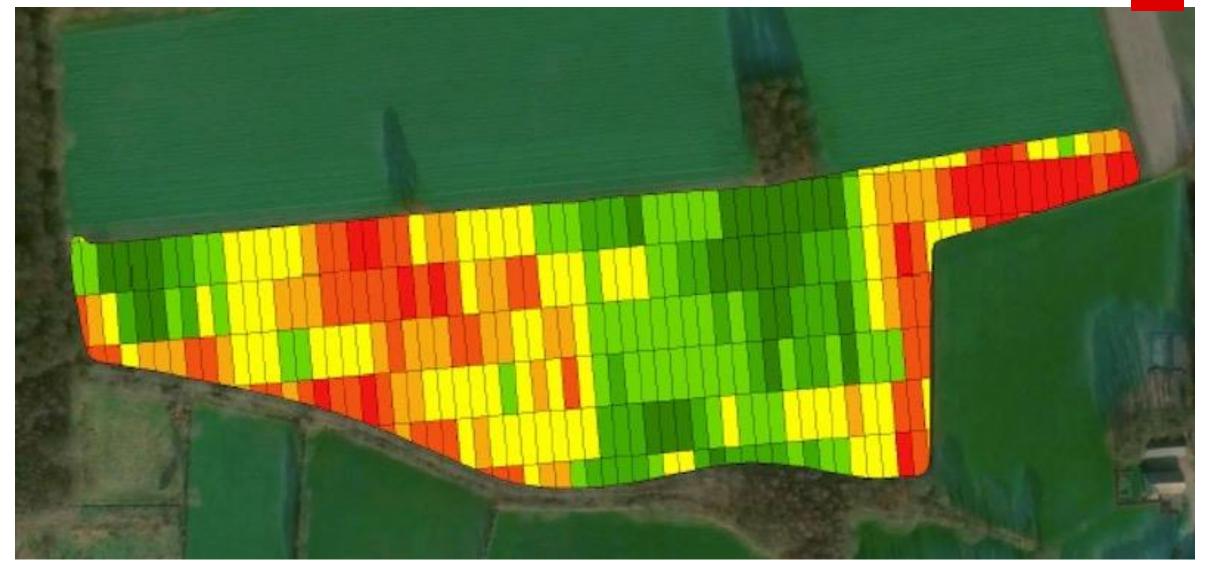
realsense: 340, zed2i: 280 Total: 620,

Processed:

2025-06-3



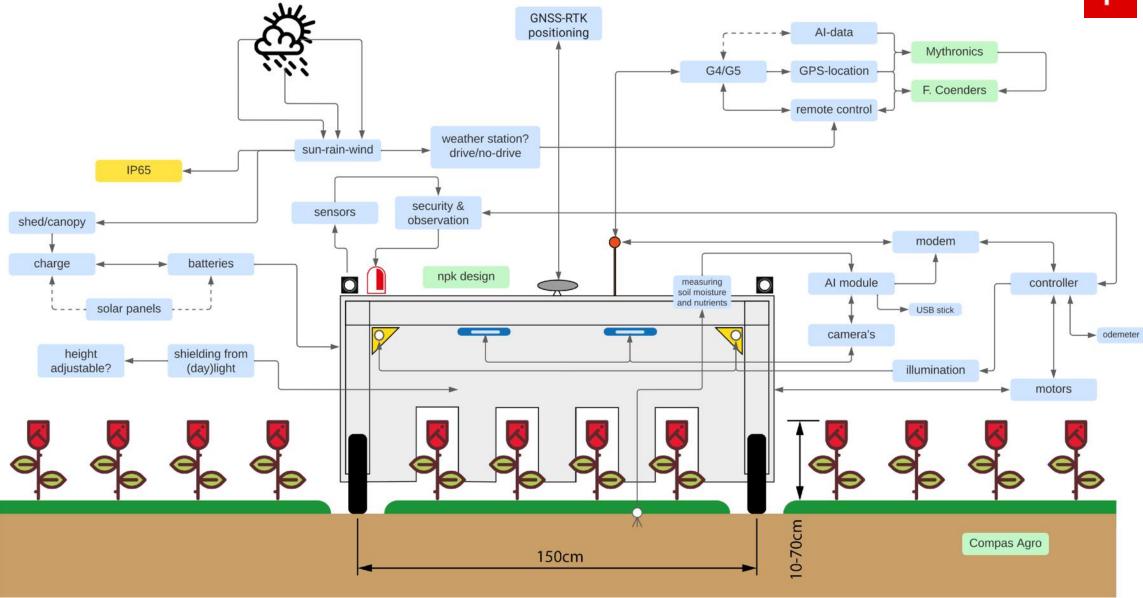




Bringing vision to reality.



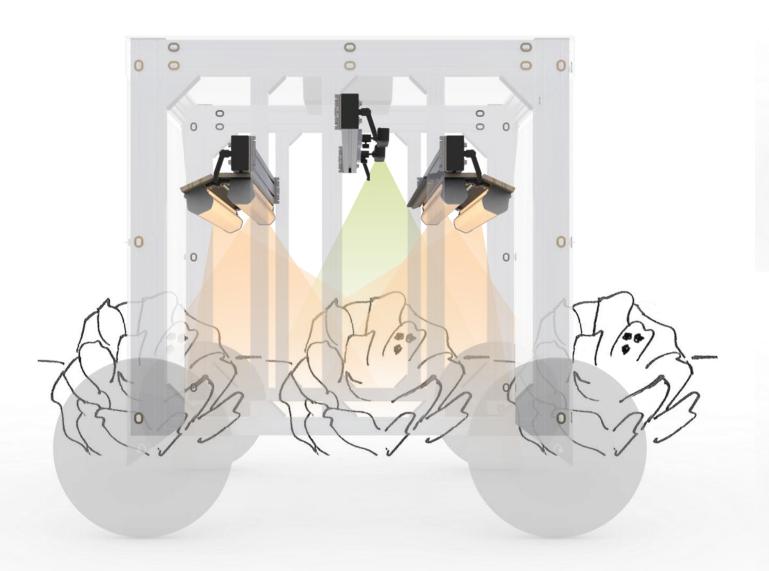


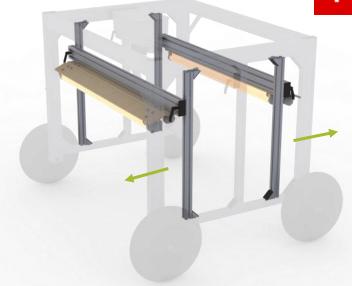


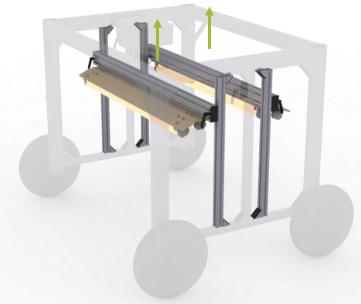
Phase and duration	1 2024 (May, June)	2 2024 (July - October)	3 2025 (May - October)	2026 (May - October)
	Seedlings plan	ted Test runs	Year 2	Year 3
Vegetation phase				
Main topic	Pre Testing	Al Training	Functional Testing	Experiment monitoring, final validation
Vehicle Mobility Status	Static	Semi-mobile (manual, no steering)	(semi) autonomous	Autonomous
Al System Status	Definition of image requirements	Image gathering for teaching AI system	Taught, testing, optimisation and finalisation	Fully operational, in demonstration for monitoring
Vehicle Status	Mounting base for cameras and lights	Moving base for cameras, lights and shading, functional model	Base for cameras, lights and shade on autonomous ready base module	Base for cameras, lights and shade on autonomous ready base module
Environment	Lab Environment (Photostudio npk)	Greenhouse / test field	Test field / real field	Real field
npk design	Base preparation	First functional tests with movable base	Integration of results onto autonomous platform	Optimisation and validation of integrated autonomous platform
Mythronics	Definition of lights and cameras	Image gathering for AI training / AI training / dev. of App	Demonstration and optimisation of Al based mildew detection	Demonstration and optimisation of Al based mildew detection
Compas Agro		Application for image gathering	Application for testing and optimisation	Conducting bio-input testing, application of vehicle for testing, optimisation and validation

Phase and duration	1 2024 (May, June)	2 2024 (July - October)	3 2025 (May - October)	2026 (May - October)
	Seedlings plan	ted Test runs	Year 2	Year 3
Vegetation phase				
Main topic	Pre Testing	Al Training	Functional Testing	Experiment monitoring, final validation
Vehicle Mobility Status	Static		(semi) autonomous	
Al System Status	Definition of image requirements	Image gathering for teaching Al system		
Vehicle Status	Mounting base for cameras and lights	Moving base for cameras, lights and shading, functional model		
Environment	Lab Environment (Photostudio npk)	Greenhouse / test field	Test field / real field	
npk design	Base preparation	First functional tests with movable base	Integration of results onto autonomous platform	Optimisation and validation of integrated autonomous platform
Mythronics	Definition of lights and cameras	Image gathering for AI training / AI training / dev. of App	Demonstration and optimisation of Al based mildew detection	Demonstration and optimisation of Al based mildew detection
Compas Agro		Application for image gathering	Application for testing and optimisation	Conducting bio-input testing, application of vehicle for testing, optimisation and validation







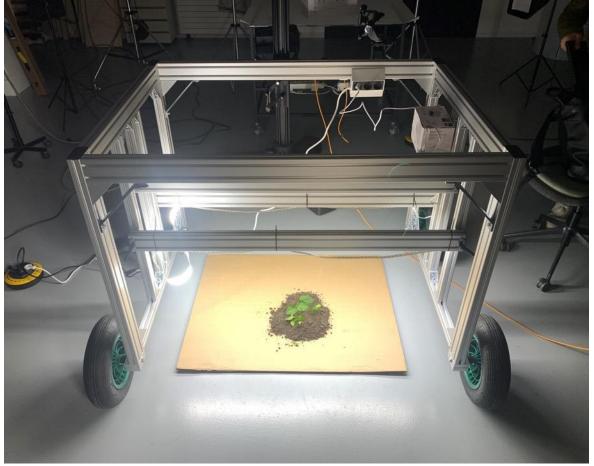


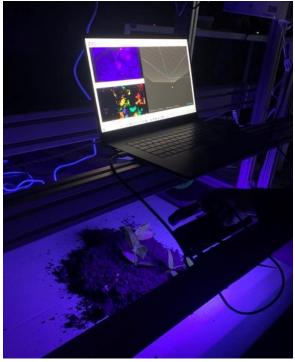


Build to learn — Unlocking insights through prototyping.





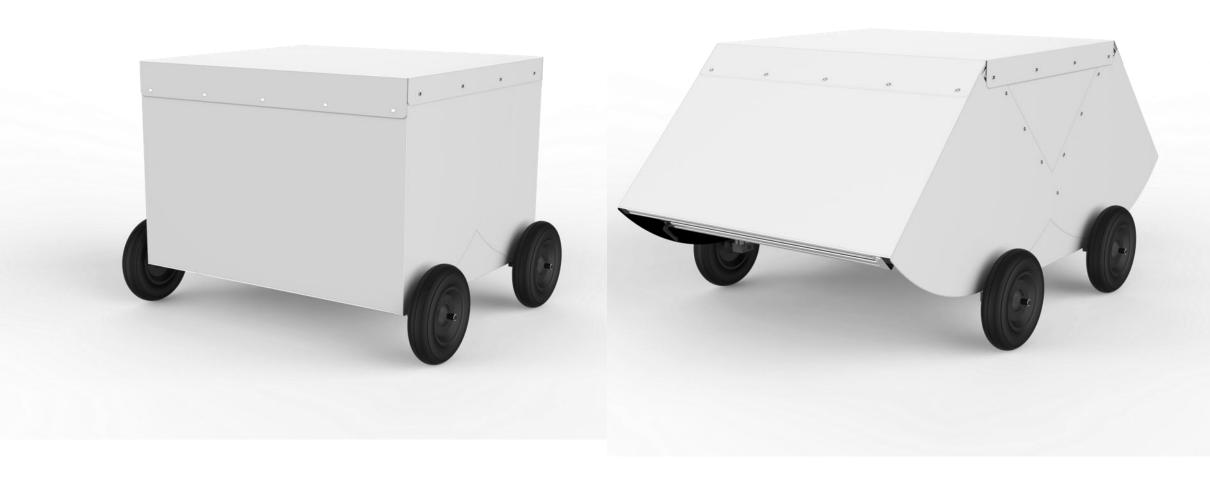




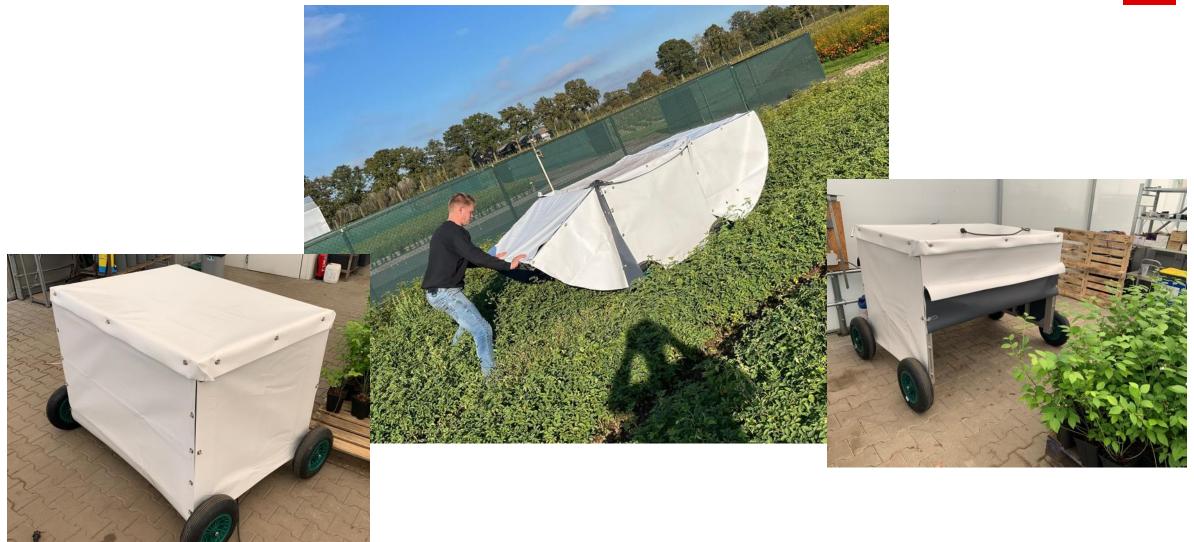
Phase and duration	1 2024 (May, June)	2024 (July - October)	3 2025 (May - October)	2026 (May - October)
	Seedlings plan	ted Test runs	Year 2	Year 3
Vegetation phase				
Main topic	Pre Testing	Al Training	Functional Testing	Experiment monitoring, final validation
Vehicle Mobility Status		Semi-mobile (manual, no steering)	(semi) autonomous	
Al System Status		Image gathering for teaching Al system		
Vehicle Status		Moving base for cameras, lights and shading, functional model		
Environment		Greenhouse / test field	Test field / real field	
npk design	Base preparation	First functional tests with movable base	Integration of results onto autonomous platform	Optimisation and validation of integrated autonomous platform
Mythronics	Definition of lights and cameras	Image gathering for AI training / AI training / dev. of App	Demonstration and optimisation of Al based mildew detection	Demonstration and optimisation of Al based mildew detection
Compas Agro		Application for image gathering	Application for testing and optimisation	Conducting bio-input testing, application of vehicle for testing, optimisation and validation



Let's provide shading!





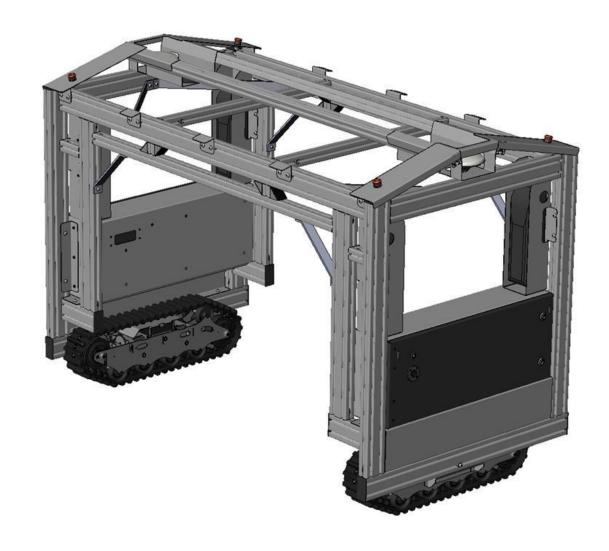


Project ROSIE—Year 1 Testing: on test fields of Compas Agro (Venlo) and on the rose nursery of Frank Coenders Rose nursery (Grubbenvorst)

Phase and duration	1 2024 (May, June)	2 2024 (July - October)	3 2025 (May - October)	2026 (May - October)
	Seedlings plan	nted Test runs	Year 2	Year 3
Vegetation phase				
Main topic	Pre Testing	Al Training	Functional Testing	Experiment monitoring, final validation
Vehicle Mobility Status			(semi) autonomous	
Al System Status		Image gathering for teaching Al system	Taught, testing, optimisation and finalisation	
Vehicle Status		Moving base for cameras, lights and shading, functional model	Base for cameras, lights and shade on autonomous ready base module	
Environment		Greenhouse / test field	Test field / real field	
npk design	Base preparation	First functional tests with movable base	Integration of results onto autonomous platform	Optimisation and validation of integrated autonomous platform
Mythronics	Definition of lights and cameras	Image gathering for AI training / AI training / dev. of App	Demonstration and optimisation of Al based mildew detection	Demonstration and optimisation of Al based mildew detection
Compas Agro		Application for image gathering	Application for testing and optimisation	Conducting bio-input testing, application of vehicle for testing, optimisation and validation



Let's make it drive-able!

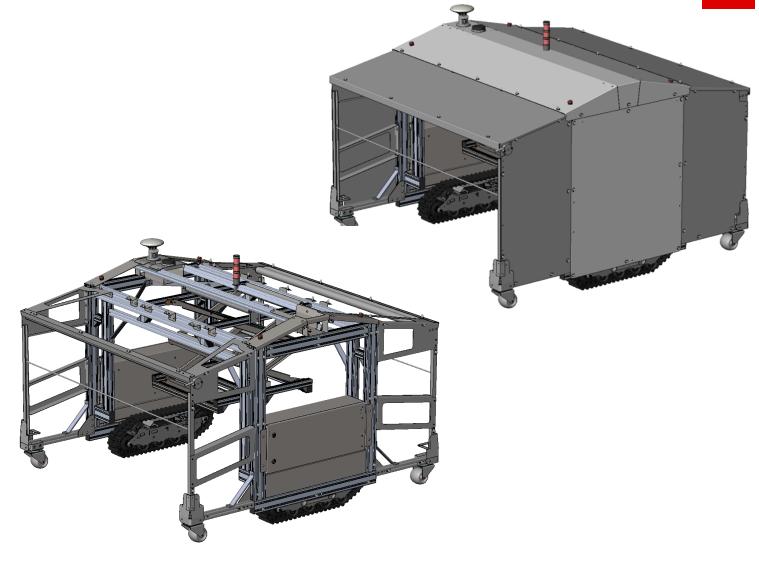






Project ROSIE — Chassis Design









Let's make it autonomous drive-able!

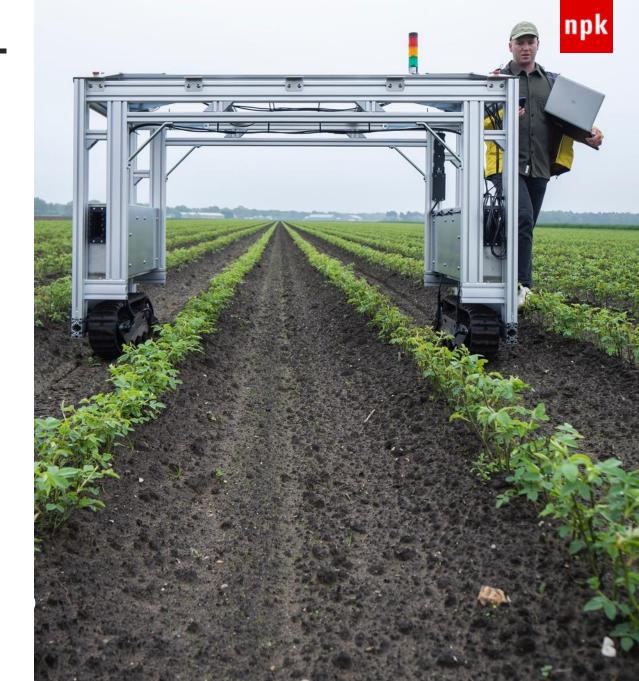




The road forward — what's next?

- 1. Meeldauw bij rozen
- 2. Roest op prei
- 3. Bestrijding van knolcyperus
- 4. Plaagdetectie bij boomkwekerij

What can we help you with right now?





Marcel Vroom M.Sc mvroom@npk.nl +31 622 465 161 www.npk.nl

n p k design

strategic product innovation